

Modelling of concurrent processes in DMBI logic

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Resources

- Resource is a key notion in computer science:

- Memory
- Processes
- Messages

- Different concerns about resources:

- Location
- Ownership
- Access to
- Consumption of

► Study of resources and related notions through logics

Introduction - resource logics

Bunched Implications (BI) logic (O'Hearn and Pym 1999, Pym 2002)

- **BI** = $\left\{ \begin{array}{l} \wedge, \vee, \rightarrow, \top, \perp \text{ (additives)} \\ *, -*, \text{I (multiplicatives)} \end{array} \right.$

BI (intuitionistic additives) , **BBI** (classical additives)

- Sequents with bunches (trees of formulae where internal nodes are ", " or ";"): $\frac{\Gamma, \phi \vdash \psi}{\Gamma \vdash \phi -* \psi} \quad \frac{\Gamma; \phi \vdash \psi}{\Gamma \vdash \phi \rightarrow \psi}$

- Bunches can be viewed as areas of a model:

$$A, (B; C), A \rightsquigarrow \boxed{A \quad B \quad C \quad A}$$

- Resources are areas and propositional symbols are properties of resources (areas)
- **BI** and **BBI** focus on separation (,) / sharing (;)

Separation logics

- **BI** and **BBI** logical kernels of separation logics
- Some separation logics:
 - **PL**: Pointer (Separation) Logic with $(x \mapsto a, b)$ (O'Hearn et al. 2001)
 - **BI-Loc**: Separation Logic with locations (Biri-Galmiche 2007)
 - **MBI**: Separation Logic with modalities for processes $(R, E \xrightarrow{a} R', E')$ (Pym-Toft 2006)
 - **DBI**: Separation Logic with modalities for dynamic properties of resources (Courtault-Galmiche 2013)

► Study of dynamics in resource/separation logics

Dynamics in resource logics

- What are systems with dynamic resources?
 - Systems that transform resources (producers / consumers)
 - Systems that modify resource properties (value of cells of a cellular automata): no resource production/consumption
- Resource logics and dynamics
 - **BI**: Properties on resources = no dynamics
 - **MBI** ($R, E \xrightarrow{a} R', E'$): Dynamics is resource transformation
 - **DBI** (**BI** + \diamond, \square): Dynamic properties of resources

MBI and SCRP (Pym-Tofte 2006)

■ SCRP: Synchronous Calculus of Resources and Processes

- Processes: $E ::= 0 \mid X \mid a : E \mid E + E \mid E \times E \mid \nu R.E \mid \text{fix}_i X.E$
- **SCRP** transitions (some rules):

$$\frac{}{R, a : E \xrightarrow{a} \mu(a, R), E} \quad (\mu(a, R) \downarrow) \quad \frac{R, E \xrightarrow{a} R', E' \quad S, F \xrightarrow{b} S', F'}{R \circ S, E \times F \xrightarrow{a\#b} R' \circ S', E' \times F'} \quad (R \circ S \downarrow)$$

■ MBI: BI/BBI + modalities ($\langle a \rangle$, $[a]$, $\langle a \rangle_\nu$, $[a]_\nu$)

■ Forcing relation:

- $R, E \vDash \phi * \psi$ iff $\exists R_1, R_2, E_1, E_2 \cdot R = R_1 \circ R_2$ and $E \sim E_1 \times E_2$ and $R_1, E_1 \vDash \phi$ and $R_2, E_2 \vDash \psi$
- $R, E \vDash \langle a \rangle \phi$ iff $\exists R', E' \cdot R, E \xrightarrow{a} R', E'$ and $R', E' \vDash \phi$
- $R, E \vDash \langle a \rangle_\nu \phi$ iff $\exists T, R', E' \cdot R \circ T, E \xrightarrow{a} R', E'$ and $R', E' \vDash \phi$

An example: mutual exclusion

- Processes:

$$E \stackrel{\text{def}}{=} nc : E + \text{critical} : E_{\text{critical}}$$

$$E_{\text{critical}} \stackrel{\text{def}}{=} \text{critical} : E_{\text{critical}} + \text{critical} : E$$

- Minimum resources required for the action: $\rho(nc) = \{e\}$ and $\rho(\text{critical}) = \{R\}$
- The μ function: $\mu(a, R) = R$ for any a action
- The action $\text{critical}\#\text{critical}$ is never performed:
 $R, E \times E \models [\text{critical}\#\text{critical}] \perp$
- Remarks:
 - Only a calculus with bunches and without completeness
 - $R, E \times E \models [\text{critical}\#\text{critical}] \perp$ does not mean that in any reachable state, couple (resource, process), it is impossible to execute two concurrent critical actions (**need of \diamond and \square**)

DBI logic

■ Dynamic modal **BI**

- **BI** with modalities \diamond and \square
- Dynamic resource properties
- A calculus that is sound and complete

■ **DBI** models:

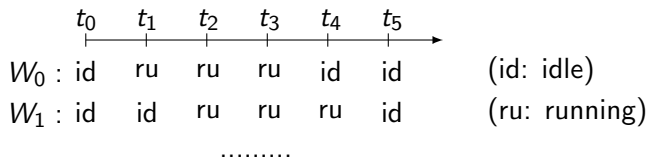
- a resource monoid: resources
- a graph: states and a state preorder (reachability)

■ Forcing relation:

- $r, s \vDash \phi * \psi$ iff $\exists r_1, r_2 \cdot r_1 \bullet r_2 \sqsubseteq r$ and $r_1, s \vDash \phi$ and $r_2, s \vDash \psi$
(remark: $*$ separates only the resource r)
- $r, s \vDash \diamond \phi$ iff $\exists s' \cdot s \preceq s'$ and $r, s' \vDash \phi$

An example: properties on states of webservices

- A set of composed webservices $W = \{W_0, W_1, W_2, W_3, \dots\}$
- A model:

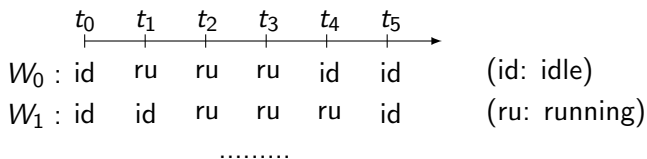


- An interpretation $\llbracket \cdot \rrbracket$:
 - $\llbracket P_{idle} \rrbracket = \{(S, t_i) \mid \exists W_i \in S \cdot W_i \text{ is } \textit{idle} \text{ at time } t_i\}$
 - $\llbracket P_{running} \rrbracket = \{(S, t_i) \mid \exists W_i \in S \cdot W_i \text{ is } \textit{running} \text{ at time } t_i\}$

where $S \subseteq W$ is a set of webservices.

For example: $S, t \models P_{idle}$ if there is at least a webservice in S that is idle at time t

An example: properties on states of webservices



■ Properties that can be expressed:

- $\{W_0, W_1\}, t_1 \models P_{idle}$
- $\{W_0, W_1\}, t_1 \models P_{idle} \wedge P_{idle}$ but $\{W_0, W_1\}, t_1 \not\models P_{idle} * P_{idle}$
- $\{W_0, W_1\}, t_0 \models P_{idle} * P_{idle}$
- $\{W_0, W_1\}, t_0 \models (P_{idle} * P_{idle}) \wedge \diamond(P_{idle} * P_{running})$

- ### ■ Remark: resource transformation cannot be express in **DBI**
- (it is not possible to model the messages that are produced / exchanged by the webservices)

Some results

- **DMBI** logic
 - captures resource transformation (\approx **MBI**)
 - includes modalities \diamond and \square (\approx **DBI**)
 - restriction to only one process ($\not\approx$ **MBI**)
- Semantics: μ -dynamic resource monoids
- Expressiveness: **DMBI** models can capture n concurrent processes that manipulate resources (but no production of processes $\not\approx$ **MBI**)
- Proof theory: a tableaux method that is sound and complete
- Counter-model extraction

Plan

- 1 Language and semantics
- 2 Expressiveness
- 3 Tableaux method
- 4 Counter-model extraction
- 5 Conclusions - Perspectives

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Language

- **DMBI** = **BBI** + $\langle a \rangle$ $[a]$ \diamond \square :

$$\phi ::= p \mid \perp \mid \top \mid \phi \rightarrow \psi \mid \phi * \psi \mid \phi \multimap \psi \mid \langle a \rangle \phi \mid [a] \phi \mid \diamond \phi \mid \square \phi$$

- Syntactic sugar:

$$\neg \phi \equiv \phi \rightarrow \perp$$

$$\top \equiv \neg \perp$$

$$\phi \vee \psi \equiv \neg \phi \rightarrow \psi$$

$$\phi \wedge \psi \equiv \neg(\phi \rightarrow \neg \psi)$$

$$[a] \phi \equiv \neg \langle a \rangle \neg \phi$$

$$\square \phi \equiv \neg \diamond \neg \phi$$

Semantics

- Resource monoid: $\mathcal{R} = (R, \bullet, e)$
 - R is a set of *resources*
 - $e \in R$ is the unit resource
 - $\bullet : R \times R \rightarrow R$ such that, for any $r_1, r_2, r_3 \in R$:
 - Neutral element: $r_1 \bullet e = e \bullet r_1 = r_1$
 - Commutativity: $r_1 \bullet r_2 = r_2 \bullet r_1$
 - Associativity: $r_1 \bullet (r_2 \bullet r_3) = (r_1 \bullet r_2) \bullet r_3$

Remark: \bullet is total because a resource is viewed as a multiset of atomic resources

Semantics

- Action monoid (non commutative): $\mathcal{A} = (Act, \odot, 1)$
 - Act is a set of *actions*
 - $1 \in Act$ is the unit action
 - $\odot : Act \times Act \rightarrow Act$ such that, for any $a_1, a_2, a_3 \in Act$:
 - Neutral element: $a_1 \odot 1 = 1 \odot a_1 = a_1$
 - Associativity: $a_1 \odot (a_2 \odot a_3) = (a_1 \odot a_2) \odot a_3$

Remark: actions are viewed as lists of atomic actions

Semantics

- A μ -dynamic resource monoid: $\mathcal{M} = (\mathcal{R}, \mathcal{A}, S, \|\cdot\|, \mu)$
 - S is a set of *states*
 - $\|\cdot\| \subseteq S \times \text{Act} \times S$, such that:
 - $\|\cdot\|$ -unit: $s_1 \|\mathbf{1}\| s_1$
 - $\|\cdot\|$ -composition: if $s_1 \|a_1\| s_2$ and $s_2 \|a_2\| s_3$ then $s_1 \|a_1 \odot a_2\| s_3$
 - $\mu : \text{Act} \times R \rightarrow R$, such that:
 - μ -unit: $\mu(\mathbf{1}, r) \downarrow$ and $\mu(\mathbf{1}, r) = r$
 - μ -composition: if $\mu(a_1, r) \downarrow$ and $\mu(a_2, \mu(a_1, r)) \downarrow$ then $\mu(a_1 \odot a_2, r) \downarrow$ and $\mu(a_1 \odot a_2, r) = \mu(a_2, \mu(a_1, r))$
- Denotations:
 - $r, s \xrightarrow{a} r', s'$ iff $\mu(a, r) \downarrow$, $\mu(a, r) = r'$ and $s \|a\| s'$
 - $r, s \rightsquigarrow r', s'$ iff $r, s \xrightarrow{a_0} r_1, s_1 \xrightarrow{a_1} \dots \xrightarrow{a_{n-1}} r_n, s_n \xrightarrow{a_n} r', s'$

Semantics

- μ -Model: $\mathcal{K} = (\mathcal{M}, \llbracket \cdot \rrbracket, | \cdot |, \models_{\mathcal{K}})$
 - $r, s \models_{\mathcal{K}} p$ iff $(r, s) \in \llbracket p \rrbracket$
 - $r, s \models_{\mathcal{K}} \perp$ never
 - $r, s \models_{\mathcal{K}} \text{I}$ iff $r = e$
 - $r, s \models_{\mathcal{K}} \phi \rightarrow \psi$ iff $r, s \models_{\mathcal{K}} \phi \Rightarrow r, s \models_{\mathcal{K}} \psi$
 - $r, s \models_{\mathcal{K}} \phi * \psi$ iff $\exists r_1, r_2 \in R \cdot r = r_1 \bullet r_2$ and $r_1, s \models_{\mathcal{K}} \phi$ and $r_2, s \models_{\mathcal{K}} \psi$
 - $r, s \models_{\mathcal{K}} \phi \multimap \psi$ iff $\forall r' \in R \cdot r', s \models_{\mathcal{K}} \phi \Rightarrow r \bullet r', s \models_{\mathcal{K}} \psi$
 - $r, s \models_{\mathcal{K}} \langle a \rangle \phi$ iff $\exists r' \in R \cdot \exists s' \in S \cdot r, s \xrightarrow{|a|} r', s'$ and $r', s' \models_{\mathcal{K}} \phi$
 - $r, s \models_{\mathcal{K}} \Diamond \phi$ iff $\exists r' \in R \cdot \exists s' \in S \cdot r, s \rightsquigarrow r', s'$ and $r', s' \models_{\mathcal{K}} \phi$
- Validity: ϕ is *valid* iff $r, s \models_{\mathcal{K}} \phi$ for any \mathcal{K} , r and s

Plan

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Concurrent processes modelling

- A user gives a description \mathcal{D} of n concurrent processes (P_1, \dots, P_n) , where $n \geq 1$:

$\mathcal{D} = (R_{atom}, Act_{atom}, \mu_{pre}, \mu_{post}, \{P_1, \dots, P_n\})$, such that:

- R_{atom} is a set of *atomic resources*
- Act_{atom} is a set of *atomic actions*
- $\mu_{pre} : Act_{atom} \rightarrow \mathfrak{M}(R_{atom})$
 $\Rightarrow \mu_{pre}(a)$ is the multiset of resources *consumed* when a process performs the action a
- $\mu_{post} : Act_{atom} \rightarrow \mathfrak{M}(R_{atom})$
 $\Rightarrow \mu_{post}(a)$ is the multiset of resources *produced* when a process performs the action a
- $P_i = (S_i, \rightarrow_{P_i})$ are processes: S_i is the set of states of P_i and $\rightarrow_{P_i} \subseteq S_i \times Act_{atom} \times S_i$ is the transition relation of P_i

► We aim to construct a μ -model that models \mathcal{D}

Concurrent processes modelling - Resources

■ Denotations for resources:

- $\mathfrak{M}(R_{atom})$ is the set of all multisets over R_{atom}
(functions $R_{atom} \rightarrow \mathbb{N}$)
- e is the empty multisets ($\forall r \in R_{atom} \cdot e(r) = 0$)
- $R_1 \leq R_2$ iff $R_1(r) \leq R_2(r)$ for all $r \in R_{atom}$
- $R_1 + R_2 = R_3$ such that $R_3(r) = R_1(r) + R_2(r)$ for all $r \in R_{atom}$
- $R_1 - R_2 = R_3$ such that $R_3(r) = R_1(r) - R_2(r)$ for all $r \in R_{atom}$
Remark: $R_1 - R_2$ is defined iff $R_2 \leq R_1$.

Concurrent processes modelling - System transitions

- Two denotations for behaviour of the system:

$$- R \left\{ \begin{array}{ccc} s_1 & \xrightarrow{a_1} P_1 & s'_1 \\ \vdots & & \vdots \\ s_n & \xrightarrow{a_n} P_n & s'_n \end{array} \right\} R' \text{ iff}$$

$$\mu_{pre}(a_1) + \dots + \mu_{pre}(a_n) \leq R \text{ and}$$

$$R' = R - \mu_{pre}(a_1) - \dots - \mu_{pre}(a_n) + \mu_{post}(a_1) + \dots + \mu_{post}(a_n)$$

$$\text{and } s_i \xrightarrow{a_i} P_i \text{ } s'_i \text{ for all } i \in \{1, \dots, n\}.$$

$$- R \left\{ \begin{array}{ccc} s_1 & \dashrightarrow P_1 & s'_1 \\ \vdots & & \vdots \\ s_n & \dashrightarrow P_n & s'_n \end{array} \right\} R' \text{ iff}$$

$$R \left\{ \begin{array}{ccc} s_1 & \xrightarrow{a_1^1} P_1 & s_1^1 \\ \vdots & & \vdots \\ s_n & \xrightarrow{a_n^1} P_n & s_n^1 \end{array} \right\} R_1 \dots R_{k-1} \left\{ \begin{array}{ccc} s_1^{k-1} & \xrightarrow{a_1^k} P_1 & s'_1 \\ \vdots & & \vdots \\ s_n^{k-1} & \xrightarrow{a_n^k} P_n & s'_n \end{array} \right\} R'$$

Concurrent processes modelling - Synchronous/Asynchronous

■ Synchronous VS asynchronous processes:

- At each transition all processes perform an action:

⇒ synchronous processes

- How to model asynchronous processes?

- By considering an atomic action *skip*

- $\mu_{pre}(skip) = \mu_{post}(skip) = e$

- $s_i \xrightarrow{skip}_{P_i} s_i$ for all processes P_i and all states $s_i \in S_i$

- Example: $R \left\{ \begin{array}{l} s_1 \xrightarrow{a_1}_{P_1} s'_1 \\ s_2 \xrightarrow{skip}_{P_2} s_2 \\ s_3 \xrightarrow{a_3}_{P_3} s'_3 \end{array} \right\} R'$

⇒ only P_1 and P_3 perform an action in this step

Concurrent processes modelling - Actions

■ Denotations for actions:

- We define $Act_{atom}^{\#} = \{a_1\#\dots\#a_n \mid a_1, \dots, a_n \in Act_{atom}\}$
 $\Rightarrow a_1\#a_2$ is a *concurrent atomic action* where P_1 performs a_1 and P_2 performs a_2 .
- We define $\mathfrak{L}(Act_{atom}^{\#})$ the set of all lists built on $Act_{atom}^{\#}$:
For example $[a_1\#a_2\#a_3; a'_1\#a'_2\#a'_3]$ is an action that consists to perform $a_1\#a_2\#a_3$ and then $a'_1\#a'_2\#a'_3$
- $[\]$ is the empty list
- \oplus is the concatenation of lists

Propositions

- 1 $\mathcal{R} = (\mathfrak{M}(R_{atom}), +, e)$ is a resource monoid.
- 2 $\mathcal{A} = (\mathfrak{L}(Act_{atom}^{\#}), \oplus, [\])$ is an action monoid

Concurrent processes modelling - States and the μ function

■ Denotations for states:

- $S^\# = \{s_1\# \dots \# s_n \mid s_i \in S_i \text{ for any } 1 \leq i \leq n\}$
 $\Rightarrow s_1\#s_2$ is the state such that P_1 is in state s_1 and P_2 is in state s_2 .

■ Denotations for the μ function:

- $\mu^\# : Act_{atom}^\# \times \mathfrak{M}(R_{atom}) \rightarrow \mathfrak{M}(R_{atom})$

$$\mu^\#(a_1\# \dots \# a_n, R) = \begin{cases} \uparrow & \text{if } \mu_{pre}(a_1) + \dots + \mu_{pre}(a_n) \not\leq R \\ R - \mu_{pre}(a_1) - \dots - \mu_{pre}(a_n) \\ \quad + \mu_{post}(a_1) + \dots + \mu_{post}(a_n) & \text{otherwise} \end{cases}$$

- $\mu_{list} : \mathfrak{L}(Act_{atom}^\#) \times \mathfrak{M}(R_{atom}) \rightarrow \mathfrak{M}(R_{atom})$

$$\mu_{list}(L, R) = \begin{cases} R & \text{if } L = [] \\ \uparrow & \text{if } L = [A_1; \dots; A_k] \text{ and } \mu^\#(A_1, R) \uparrow \\ \mu_{list}([A_2; \dots; A_k], \mu^\#(A_1, R)) & \text{where } L = [A_1; \dots; A_k] \end{cases}$$

Concurrent processes modelling - State/resource relation

- Denotations for the relation on states and resources:

$$- |\cdot\rangle^{\#} : S^{\#} \times Act_{atom}^{\#} \times S^{\#}$$

$$s_1\# \dots \# s_n | a_1\# \dots \# a_n \rangle^{\#} s'_1\# \dots \# s'_n \text{ iff } s_i \xrightarrow{a_i}_{P_i} s'_i \text{ for all } 1 \leq i \leq n$$

$$- |\cdot\rangle_{list} : S^{\#} \times \mathcal{L}(Act_{atom}^{\#}) \times S^{\#}$$

$$S |[A_1; \dots; A_k]\rangle_{list} S' \text{ iff } S |A_1\rangle^{\#} S_1 |A_2\rangle^{\#} \dots |A_{k-1}\rangle^{\#} S_{k-1} |A_k\rangle^{\#} S'$$

Lemma

Let $\mathcal{D} = (R_{atom}, Act_{atom}, \mu_{pre}, \mu_{post}, \{P_1, \dots, P_n\})$, where $P_i = (S_i, \rightarrow_{P_i})$.

$\mathcal{M} = (\mathcal{R}, \mathcal{A}, S^{\#}, |\cdot\rangle_{list}, \mu_{list})$, where $\mathcal{R} = (\mathfrak{M}(R_{atom}), +, e)$ and where $\mathcal{A} = (\mathcal{L}(Act_{atom}^{\#}), \oplus, [])$ is a μ -DRM.

Concurrent processes modelling - Reachability/Satisfiability

■ Denotations:

$$- \llbracket \cdot \rrbracket : Prop \rightarrow \mathbb{P}(\mathfrak{M}(R_{atom}) \times S^\#)$$

$$\llbracket r_i \rrbracket = \{(\{r_i\}, s) \mid s \in S^\#\}$$

$$- |\cdot| : S_{Act} \rightarrow \mathcal{L}(Act_{atom}^\#)$$

$$|a_1\# \dots \# a_n| = [a_1\# \dots \# a_n]$$

$$- \hat{\cdot} : \mathfrak{M}(R_{atom}) \rightarrow \mathcal{L}:$$

$$\hat{R} = \begin{cases} I & \text{if } R = e \\ r_1 * \dots * r_k & \text{if } R = \{r_1, \dots, r_k\} \end{cases}$$

Concurrent processes modelling - Reachability/Satisfiability

Lemma

$$R \left\{ \begin{array}{ccc} s_1 & \xrightarrow{a_1} P_1 & s'_1 \\ \vdots & & \vdots \\ s_n & \xrightarrow{a_n} P_n & s'_n \end{array} \right\} R' \text{ iff } R, s_1 \# \dots \# s_n \xrightarrow{[a_1 \# \dots \# a_n]} R', s'_1 \# \dots \# s'_n$$

Lemma

$$R \left\{ \begin{array}{ccc} s_1 & \dashrightarrow P_1 & s'_1 \\ \vdots & & \vdots \\ s_n & \dashrightarrow P_n & s'_n \end{array} \right\} R' \text{ iff } R, s_1 \# \dots \# s_n \rightsquigarrow R', s'_1 \# \dots \# s'_n$$

Concurrent processes modelling - Reachability/Satisfiability

Theorem

$$R \left\{ \begin{array}{ccc} s_1 & \xrightarrow{a_1} P_1 & s'_1 \\ \vdots & & \vdots \\ s_n & \xrightarrow{a_n} P_n & s'_n \end{array} \right\} R' \text{ iff } R, s_1 \# \dots \# s_n \vDash_{\mathcal{K}} \langle a_1 \# \dots \# a_n \rangle \widehat{R'}$$

Theorem

$$R \left\{ \begin{array}{ccc} s_1 & \dashrightarrow P_1 & s'_1 \\ \vdots & & \vdots \\ s_n & \dashrightarrow P_n & s'_n \end{array} \right\} R' \text{ iff } R, s_1 \# \dots \# s_n \vDash_{\mathcal{K}} \diamond \widehat{R'}$$

Concurrent processes modelling - Mutual exclusion

- Mutual exclusion (revisited):

$\mathcal{D} = (R_{atom}, Act_{atom}, \mu_{pre}, \mu_{post}, \{P_1, P_2\})$, where:

- $R_{atom} = \{J\}$
- $Act_{atom} = \{a_{nc}, a_c, a_p, a_v\}$
- μ_{pre} is defined by:
 - $\mu_{pre}(a_{nc}) = \mu_{pre}(a_c) = \mu_{pre}(a_v) = e$
 - $\mu_{pre}(a_p) = J$
- μ_{post} is defined by:
 - $\mu_{post}(a_{nc}) = \mu_{post}(a_c) = \mu_{post}(a_p) = e$
 - $\mu_{post}(a_v) = J$
- $P_1 = (S_1, \rightarrow_{P_1})$ and $P_2 = (S_2, \rightarrow_{P_2})$ such that:
 - $S_1 = S_2 = \{s_{nc}, s_c\}$
 - For any $i \in \{1, 2\}$, we have:

$$S_{nc} \xrightarrow{a_{nc}}_{P_i} S_{nc} \quad S_{nc} \xrightarrow{a_p}_{P_i} S_c \quad S_c \xrightarrow{a_c}_{P_i} S_c \quad S_c \xrightarrow{a_v}_{P_i} S_{nc}$$

Concurrent processes modelling - Mutual exclusion

■ Mutual exclusion (revisited):

- We construct $\mathcal{M} = (\mathcal{R}, \mathcal{A}, S^\#, |\cdot\rangle_{list}, \mu_{list})$, where $\mathcal{R} = (\mathfrak{M}(R_{atom}), +, e)$ and where $\mathcal{A} = (\mathfrak{L}(Act^\#_{atom}), \oplus, [])$
- "After performing any succession of actions, the processes can not perform together a critical action":

$$\{J\}, s_{nc} \# s_{nc} \models_{\mathcal{K}} \Box [a_c \# a_c] \perp$$

- "It is impossible to reach a state such that more than one token is available":

$$\{J\}, s_{nc} \# s_{nc} \models_{\mathcal{K}} \neg \Diamond (J * J * \top)$$

■ We observe that **DMBI**:

- captures resource transformation ($\not\approx$ **DBI**) (\approx **MBI**)
- expresses properties on any reachable states (\approx **DBI**) ($\not\approx$ **MBI**)
- does not model capture process production ($\not\approx$ **MBI**)

Plan

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- 2 Expressiveness
- 3 Tableaux method**
- 4 Counter-model extraction
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An extension of **BI** calculus (Galmiche-Méry-Pym 2005) based on constrained set of statements (CSS in Larchey 2012)

- Resource labels (R), action labels (Act) and state labels (S)
- Resource constraints ($=$), μ -constraints (μ) and transition constraints ($\|\cdot\|$)
- Signed formulae: $\mathbb{S}\phi : (x, u)$
- Branches are denoted $\langle \mathcal{F}, \mathcal{C} \rangle$ where \mathcal{C} is a set of resource, transition and μ constraints
- Assertions/requirements

Labels

- **Resource labels (L_r):**

$$X ::= 1_r \mid c_i \mid X \circ X$$

where $c_i \in \gamma_r = \{c_1, c_2, \dots\}$ and \circ is a function on L_r that is associative, commutative and 1_r is its unit. $x \circ y$ is denoted xy .

- **Action labels (L_a):**

$$X ::= 1_a \mid a_i \mid d_i \mid X \cdot X$$

where $a_i \in S_{Act}$, $d_i \in \gamma_a = \{d_1, d_2, \dots\}$, $S_{Act} \cap \gamma_a = \emptyset$ and \cdot is a function on L_a that is associative (not commutative) and 1_a is its unit. $f \cdot g$ is denoted fg .

- **State labels (L_s):** $L_s = \{l_1, l_2, \dots\}$.

Constraints

■ Resource constraints:

- encode equality on resources.
- $x \sim y$ where x and y are resource labels.

■ μ -constraints:

- encode the function μ .
- $x \xrightarrow{f} y$ where x and y are resource labels and f is an action label.

■ Transition constraints:

- Encode the function $\|\cdot\>\rangle$.
- $u \xrightarrow{f} v$ where u and v are state labels and f is an action label.

Constraint closure

- Rules that product resource constraints:

$$\frac{}{1_r \sim 1_r} \langle 1_r \rangle$$

$$\frac{x \sim y}{y \sim x} \langle s_r \rangle$$

$$\frac{xy \sim xy}{x \sim x} \langle d_r \rangle$$

$$\frac{x \sim y \quad y \sim z}{x \sim z} \langle t_r \rangle$$

$$\frac{x \sim x' \quad y \sim y'}{xy \sim x'y'} \langle g_r \rangle$$

$$\frac{x \xrightarrow{f} y \quad x \xrightarrow{f} z}{y \sim z} \langle k_r \rangle$$

$$\frac{x \xrightarrow{f} y}{x \sim x} \langle a_{r1} \rangle$$

Constraint closure

- Rules that product μ -constraints:

$$\frac{x \sim x}{x \twoheadrightarrow x} \langle 1_\mu \rangle$$

$$\frac{x \xrightarrow{f} y \quad y \xrightarrow{g} z}{x \xrightarrow{fg} z} \langle t_\mu \rangle$$

$$\frac{x \xrightarrow{f} y \quad x \sim x'}{x' \xrightarrow{f} y} \langle k_{\mu_1} \rangle$$

$$\frac{x \xrightarrow{f} y \quad y \sim y'}{x \xrightarrow{f} y'} \langle k_{\mu_2} \rangle$$

- Rules that product transition constraints:

$$\frac{u \xrightarrow{f} v}{u \xrightarrow{1_a} u} \langle 1_{t_1} \rangle$$

$$\frac{u \xrightarrow{f} v}{v \xrightarrow{1_a} v} \langle 1_{t_2} \rangle$$

$$\frac{u \xrightarrow{f} v \quad v \xrightarrow{g} w}{u \xrightarrow{fg} w} \langle t_t \rangle$$

Modal rules

- **Assertion** rules:

Introduction of new labels and assertions (or constraints)

$$\frac{\mathbb{T}\langle f \rangle \phi : (x, u) \in \mathcal{F}}{\langle \{\mathbb{T}\phi : (c_i, l_i)\}, \{x \xrightarrow{f} c_i, u \xrightarrow{f} l_i\} \rangle} \langle \mathbb{T}\langle - \rangle \rangle$$

$$\frac{\mathbb{T}\Diamond\phi : (x, u) \in \mathcal{F}}{\langle \{\mathbb{T}\phi : (c_i, l_i)\}, \{x \xrightarrow{d_i} c_i, u \xrightarrow{d_i} l_i\} \rangle} \langle \mathbb{T}\Diamond \rangle$$

- **Requirement** rules:

Conditions that must be verified in the closure of constraints

$$\frac{\mathbb{F}\langle f \rangle \phi : (x, u) \in \mathcal{F} \text{ and } x \xrightarrow{f} y \in \bar{\mathcal{C}} \text{ and } u \xrightarrow{f} v \in \bar{\mathcal{C}}}{\langle \mathbb{F}\phi : (y, v), \emptyset \rangle} \langle \mathbb{F}\langle - \rangle \rangle$$

$$\frac{\mathbb{F}\Diamond\phi : (x, u) \in \mathcal{F} \text{ and } x \xrightarrow{f} y \in \bar{\mathcal{C}} \text{ and } u \xrightarrow{f} v \in \bar{\mathcal{C}}}{\langle \{\mathbb{F}\phi : (y, v)\}, \emptyset \rangle} \langle \mathbb{F}\Diamond \rangle$$

DMBI Tableaux method

Definition: closed branch

A CSS (branch) $\langle \mathcal{F}, \mathcal{C} \rangle$ is **closed** iff one of these conditions holds:

- $\mathbb{T}\phi : (x, u) \in \mathcal{F}, \mathbb{F}\phi : (y, u) \in \mathcal{F}$ and $x \sim y \in \bar{\mathcal{C}}$
- $\mathbb{F}1 : (x, u) \in \mathcal{F}$ and $1_r \sim x \in \bar{\mathcal{C}}$
- $\mathbb{T}\perp : (x, u) \in \mathcal{F}$

Definition: μ -proof

A μ -proof for a formula ϕ is a μ -tableau for ϕ which is closed.

Theorem: soundness

If there exists a μ -proof for a formula ϕ then ϕ is valid.

Theorem: completeness

If a formula ϕ is valid then there is a μ -proof for ϕ .

DMBI Tableaux method - an example

► How to prove $\phi \equiv (I \multimap \langle a \rangle \langle b \rangle P) \rightarrow \Diamond P$?

Step 1: Initialization

$[F]$	$[C]$
$\mathbb{F}(I \multimap \langle a \rangle \langle b \rangle P) \rightarrow \Diamond P : (c_1, l_1)$	$c_1 \sim c_1 \quad l_1 \xrightarrow{1_a} l_1$

DMBI Tableaux method - an example

[\mathcal{F}]

$$\mathbb{F}(I \rightarrow * \langle a \rangle \langle b \rangle P) \rightarrow \diamond P : (c_1, h_1)$$

[\mathcal{C}]

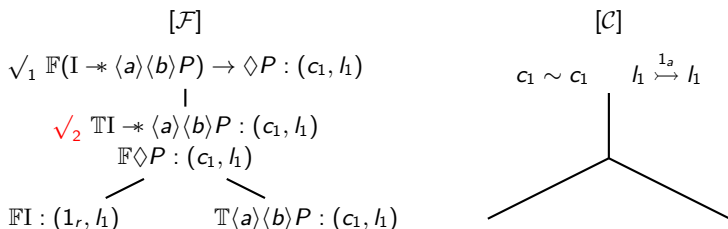
$$c_1 \sim c_1 \quad h_1 \xrightarrow{1_a} h_1$$

DMBI Tableaux method - an example

$$\begin{array}{c}
 [\mathcal{F}] \\
 \sqrt{1} \mathbb{F}(I \ast \langle a \rangle \langle b \rangle P) \rightarrow \diamond P : (c_1, h_1) \\
 | \\
 \mathbb{T}I \ast \langle a \rangle \langle b \rangle P : (c_1, h_1) \\
 \mathbb{F}\diamond P : (c_1, h_1)
 \end{array}
 \qquad
 \begin{array}{c}
 [\mathcal{C}] \\
 c_1 \sim c_1 \quad h_1 \xrightarrow{1_a} h_1 \\
 |
 \end{array}$$

$$\frac{\mathbb{F}\phi \rightarrow \psi : (x, u) \in \mathcal{F}}{\langle \mathbb{T}\phi : (x, u), \mathbb{F}\psi : (x, u) \rangle, \emptyset} \langle \mathbb{F} \rightarrow \rangle$$

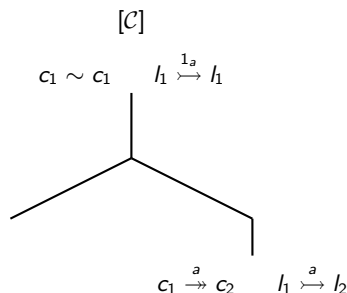
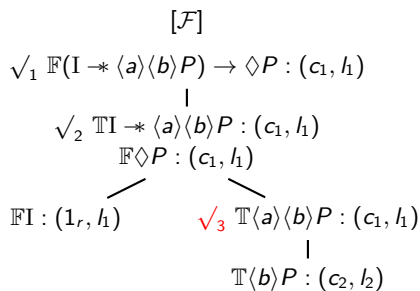
DMBI Tableaux method - an example



$$\frac{\mathbb{T}\phi \multimap \psi : (x, u) \in \mathcal{F} \text{ and } xy \sim xy \in \bar{\mathcal{C}}}{\langle \{\mathbb{F}\phi : (y, u)\}, \emptyset \mid \langle \{\mathbb{T}\psi : (xy, u)\}, \emptyset \rangle} \langle \mathbb{T}\multimap \rangle$$

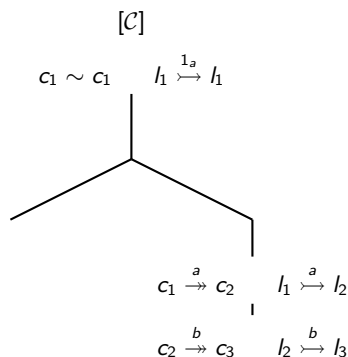
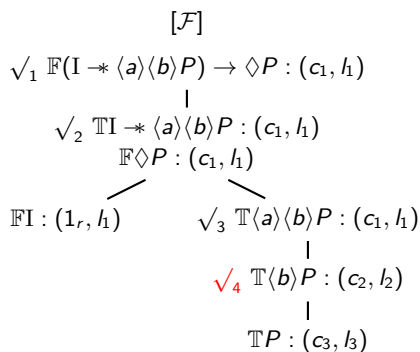
Remark: $c_1 \circ 1_r = c_1$

DMBI Tableaux method - an example



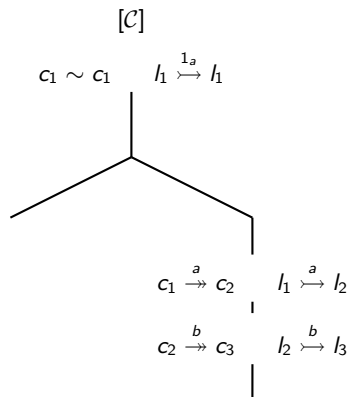
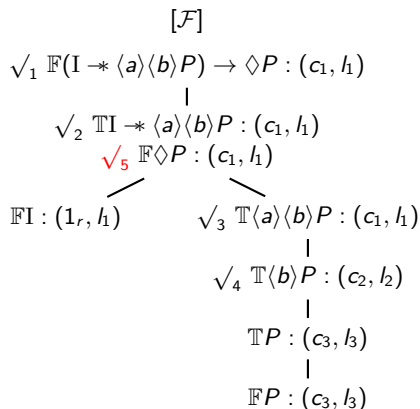
$$\frac{\mathbb{T}\langle f \rangle \phi : (x, u) \in \mathcal{F}}{\langle \{ \mathbb{T}\phi : (c_i, l_i) \}, \{ x \xrightarrow{f} c_i, u \xrightarrow{f} l_i \} \rangle} \langle \mathbb{T}(-) \rangle$$

DMBI Tableaux method - an example



$$\frac{\mathbb{T}\langle f \rangle \phi : (x, u) \in \mathcal{F}}{\langle \mathbb{T}\phi : (c_i, l_i) \rangle, \{x \xrightarrow{f} c_i, u \xrightarrow{f} l_i\}} \langle \mathbb{T}(-) \rangle$$

DMBI Tableaux method - an example

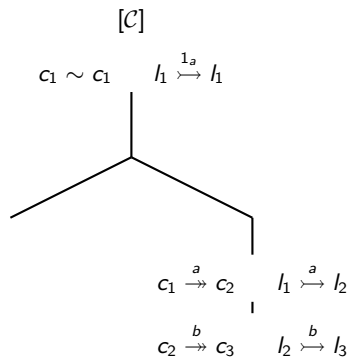
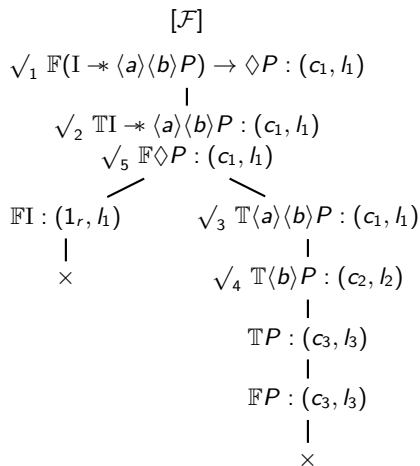


$$\frac{\mathbb{F}\diamond\phi : (x, u) \in \mathcal{F} \text{ and } x \xrightarrow{f} y \in \bar{\mathcal{C}} \text{ and } u \xrightarrow{f} v \in \bar{\mathcal{C}}}{\langle \{\mathbb{F}\phi : (y, v)\}, \emptyset \rangle} \langle \mathbb{F}\diamond \rangle$$

$$\frac{c_1 \xrightarrow{a} c_2 \quad c_2 \xrightarrow{b} c_3}{c_1 \xrightarrow{ab} c_3} \langle t_\mu \rangle \quad \frac{h_1 \xrightarrow{a} l_2 \quad h_2 \xrightarrow{b} l_3}{h_1 \xrightarrow{ab} l_3} \langle t_t \rangle$$

DMBI Tableaux method - an example

Step 2: Application of rules



The formula $(I \rightarrow * \langle a \rangle \langle b \rangle P) \rightarrow \diamond P$ is valid

Plan

- 1 Language and semantics
- 2 Expressiveness
- 3 Tableaux method
- 4 Counter-model extraction**
- 5 Conclusions - Perspectives

Counter-model extraction

Definition: Hintikka CSS

A Hintikka CSS $\langle \mathcal{F}, \bar{\mathcal{C}} \rangle$ is a unclosed branch such that "all information has been extracted":

$$1 \quad \mathbb{T}\phi : (x, u) \notin \mathcal{F} \text{ or } \mathbb{F}\phi : (y, u) \notin \mathcal{F} \text{ or } x \sim y \notin \bar{\mathcal{C}}$$

2-12 ...

$$13 \quad \text{If } \mathbb{T}\Diamond\phi : (x, u) \in \mathcal{F} \text{ then } \exists y \in L_r, \exists f \in L_a, \exists v \in L_s, x \xrightarrow{f} y \in \bar{\mathcal{C}} \text{ and } u \xrightarrow{f} v \in \bar{\mathcal{C}} \text{ and } \mathbb{T}\phi : (y, v) \in \mathcal{F}$$

$$14 \quad \text{If } \mathbb{F}\Diamond\phi : (x, u) \in \mathcal{F} \text{ then } \forall y \in L_r, \forall f \in L_a, \forall v \in L_s, (x \xrightarrow{f} y \in \bar{\mathcal{C}} \text{ and } u \xrightarrow{f} v \in \bar{\mathcal{C}}) \Rightarrow \mathbb{F}\phi : (y, v) \in \mathcal{F}$$

Lemma: counter-model extraction

A counter-model can be extracted from a Hintikka branch.

Counter-model extraction

Function Ω

Let $\langle \mathcal{F}, \mathcal{C} \rangle$ be a Hintikka CSS. $\Omega(\langle \mathcal{F}, \mathcal{C} \rangle) = (\mathcal{M}, \llbracket \cdot \rrbracket, | \cdot |, \models_{\mathcal{K}})$, such that:

- $R = \mathcal{D}_r(\bar{\mathcal{C}}) / \sim$ $S = \mathcal{A}_s(\mathcal{C})$ $Act = \mathcal{D}_a(\bar{\mathcal{C}}) \cup \{\alpha\}$ (where $\alpha \notin \mathcal{D}_a(\bar{\mathcal{C}})$)
- $e = [1_r]$
- $1 = 1_a$
- $[x] \bullet [y] = [x \circ y]$
- $\mu(a, [x]) = \begin{cases} \uparrow & \text{if } \{y \mid x \xrightarrow{a} y \in \bar{\mathcal{C}}\} = \emptyset \\ \{y \mid x \xrightarrow{a} y \in \bar{\mathcal{C}}\} & \text{otherwise} \end{cases}$
- $s_1 \parallel f \rangle s_2$ iff $s_1 \xrightarrow{f} s_2 \in \bar{\mathcal{C}}$
- For all $a_1, a_2 \in Act$, $a_1 \odot a_2 = \begin{cases} a_1 \cdot a_2 & \text{if } a_1 \cdot a_2 \in \mathcal{D}_a(\bar{\mathcal{C}}) \\ \alpha & \text{otherwise} \end{cases}$
- For all $a \in S_{Act}$, $|a| = \begin{cases} a & \text{if } a \in \mathcal{D}_a(\bar{\mathcal{C}}) \\ \alpha & \text{otherwise} \end{cases}$
- $([x], s) \in \llbracket P \rrbracket$ iff $\exists y \in L_r, x \in [y]$ and $\mathbb{T}P : (y, s) \in \mathcal{F}$

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Conclusions

A modal extension of **MBI** for resource transformations

- That captures resource transformations (\approx **MBI**)
- That includes modalities \diamond and \square (\approx **DBI**)
- That has a sound and complete calculus with a countermodel extraction method
- That can express properties resources produced by n concurrent processes that manipulate these resources

Future works

- Study is **DMBI** can capture process production
- Study extension of **DMBI** with locations and provide a sound and complete calculus
- Study other extension to express properties on:
 - Webservices
 - Protocols
 - ...