

# The dynamic logic of assignments

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# Overview

- PDL: abstract actions only

*Propositional Dynamic Logic “abstracts away from the nature of the domain of computation and studies the pure interaction between programs and propositions” [Harel et al. 2000]*

- update logics: concrete programs [van Benthem], [Baltag and Moss], [van Ditmarsch et al.], . . .

- $\varphi!$  = “ $\varphi$  is publicly announced”

- relativise model  $M$  to  $\|\varphi\|_M$ :  $W^\varphi = \|\varphi\|_M$ ,  $R^\varphi = R|_{\|\varphi\|_M}$
- alternatively:  $R^\varphi = R \cap (W \times \|\varphi\|_M)$

- $p \leftarrow \varphi$  = “ $p$  is publicly assigned the truth value of  $\varphi$ ”

- $$V^{p \leftarrow \varphi}(q) = \begin{cases} \|\varphi\|_M & \text{if } q = p \\ V(p) & \text{if } q \neq p \end{cases}$$

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- 1 The logic of public announcements and public assignments
- 2 Dynamic Logic of Propositional Assignments
- 3 Reasoning about agents' capabilities: encoding coalition logic of propositional control

## PAL-PA: language

- $\text{Prp} = \{p, q, \dots\}$  = set of propositional variables
- events:
  - $\varphi!$  = “ $\varphi$  is publicly announced”
  - $p \leftarrow \varphi$  = “ $p$  is publicly assigned the truth value of  $\varphi$ ”
    - N.B.: don't confuse with assignments of object variables  $x \leftarrow t$  of first-order Dynamic Logic
  - **lists** of public assignments
    - $\epsilon$  = empty list
    - executed in parallel
    - in case of conflict: leftmost assignments wins  
 $\alpha = (p \leftarrow \perp, p \leftarrow \top)$  makes  $p$  false
  - complex events: ...
- formulas: ...

## PAL-PA: language, ctd.

- BNF for *assignments*  $\alpha$ , *programs*  $\pi$  and *formulas*  $\varphi$ :

$$\alpha ::= \epsilon \mid (p \leftarrow \varphi, \alpha)$$

$$\pi ::= \alpha \mid \pi; \pi \mid \pi \cup \pi \mid \pi^* \mid \varphi? \mid \varphi!$$

$$\varphi ::= p \mid \top \mid \perp \mid \neg\varphi \mid \varphi \vee \varphi \mid [\pi]\varphi \mid K\varphi$$

- else just as PDL:

- skip  $\stackrel{\text{def}}{=} \top?$

- if  $\varphi$  then  $\pi_1$  else  $\pi_2 \stackrel{\text{def}}{=} \dots$

- while  $\varphi$  do  $\pi \stackrel{\text{def}}{=} \dots$

- for ease of presentation: single agent
  - but everything extends to multiagent case

# Models

- S5 models:  $M = \langle W, \sim, V \rangle$  such that
  - $W$  nonempty set
  - $\sim \subseteq W \times W$  equivalence relation
  - $V : \text{Prp} \rightarrow 2^W$  valuation
- interpretation of a formula = set of pointed models
  - $\|\varphi\| = \{(M_1, w_1), (M_2, w_2), \dots\}$
- interpretation of a modality =
  - relation on the set of pointed models
  - $\|\pi\| = \{\langle (M_1, w_1), (M'_1, w'_1) \rangle, \langle (M_2, w_2), (M'_2, w'_2) \rangle, \dots\}$

# Interpretation of formulas

business as usual:

$$\|\top\| = \{(M, w) : (M, w) \text{ is a pointed S5 model}\}$$

$$\|\perp\| = \emptyset$$

$$\|p\| = \{(M, w) : w \in V(p)\}$$

$$\|\neg\varphi\| = \dots$$

$$\|\varphi \vee \psi\| = \dots$$

$$\|\Box\varphi\| = \{(M, w) : \text{for every } (M', w') \text{ s.th. } (M, w) \|\Box\| (M', w'), \\ (M', w') \in \|\varphi\|\}$$

where  $\Box$  is any modal operator



# Interpretation of epistemic operators

change actual world  $w$  according to epistemic relation  $\sim$ :

$$(M, w) \Vdash K \Vdash (M', w') \text{ iff } \begin{cases} W' = W, \\ \sim' = \sim, \\ V' = V, \\ w' \sim w \end{cases}$$

# Interpretation of announcements

relativisation:

$$(M, w) \Vdash \varphi! \Vdash (M', w') \text{ iff } \begin{cases} W' & = W \cap \Vdash \varphi \Vdash_{\mathbf{M}}, \\ \sim' & = \sim \cap (W' \times W'), \\ V'(p) & = V(p) \cap W', \\ w' & = w \end{cases}$$

where  $\Vdash \varphi \Vdash_{\mathbf{M}}$  is the extension of  $\varphi$  in  $M$ :

$$\begin{aligned} \Vdash \varphi \Vdash_{\mathbf{M}} &= \{w : (M, w) \in \Vdash \varphi \Vdash\} \\ &= \Vdash \varphi \Vdash \cap \{(M, w) : w \text{ world of } M\} \end{aligned}$$

## Interpretation of assignments

update valuation  $V$  by list of assignments  $\alpha$ :

$$(M, w) \parallel \alpha \parallel (M', w') \quad \text{iff} \quad \begin{cases} W' & = W, \\ \sim' & = \sim, \\ V'(p) & = \parallel \alpha(p) \parallel_M, \\ w & = w' \end{cases}$$

where list applies with priority to leftmost assignments:

$$\begin{aligned} \epsilon(p) &= p \\ (q \leftarrow \varphi, \alpha)(p) &= \begin{cases} \varphi & \text{if } q = p \\ \alpha(p) & \text{if } q \neq p \end{cases} \end{aligned}$$

# Interpretation of complex programs

business as usual:

$$\begin{aligned}\|\pi_1; \pi_2\| &= \|\pi_1\| \circ \|\pi_2\| \\ \|\pi_1 \cup \pi_2\| &= \|\pi_1\| \cup \|\pi_2\| \\ \|\pi^*\| &= (\|\pi\|)^* \\ \|\varphi?\| &= \{ \langle (M, w), (M, w) \rangle : w \in \|\varphi\|_M \}\end{aligned}$$

# Satisfiability and validity

- business as usual:

$\varphi$  satisfiable    iff     $\|\varphi\| \neq \|\perp\|$

$\varphi$  is valid        iff     $\|\varphi\| = \|\top\|$

# Complexity of satisfiability for fragments of PAL-PA

- ① the whole language: undecidable [Miller&Moss 2003]
  - announcements  $\varphi!$  and Kleene star  $\pi^*$  are enough
- ② no PDL operators, no assignments: decidable [Plaza 1989]
  - monoagent case: NP complete [Lutz 2007]
  - multiagent case: PSPACE complete [Lutz 2007]
  - common knowledge: EXPTIME complete [Lutz 2007]
- ③ no complex programs: decidable [van Ditmarsch et al. 2007]
  - complexity as above [van Ditmarsch et al., JANCL 2012]
- ④ non-epistemic fragment: decidable (v.i.)
  - no complex programs: NP complete (apply reduction axioms)
  - no  $\pi^*$ : PSPACE complete [Herzig et al. IJCAI 2011]
  - whole fragment: PSPACE complete (v.i.)

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# Dynamic Logic of Propositional Assignments DL-PA

DL-PA = non-epistemic fragment of PAL-PA:

$$\pi ::= p \leftarrow \top \mid p \leftarrow \perp \mid \pi; \pi \mid \pi \cup \pi \mid \pi^* \mid \varphi?$$

- pointed model = a single valuation [v. Eijck 2000]
- $p \leftarrow \varphi$  has same interpretation as  $(\varphi?; p \leftarrow \top) \cup (\neg\varphi?; p \leftarrow \perp)$
- plus abstract actions à la PDL: undecidable  
[Tiomkin and Makowsky 1985]



## DL-PA: decision procedure

key step: eliminate the Kleene star

- 1 choose some  $\pi^*$  such that  $\pi$  is star-free
- 2 transform  $\pi$  into

$$(\varphi_1?; \alpha_1) \cup \dots \cup (\varphi_n?; \alpha_n)$$

where every  $\alpha_k$  is a sequence of assignments

- 3 make all the assignment sequences  $\alpha_k$  assign exactly the same variables:

$$(\varphi_1?; \alpha_1) \cup \dots \cup (\varphi_n?; \alpha_n) \quad \text{and} \quad \text{Prp}_{\alpha_1} = \dots = \text{Prp}_{\alpha_n}$$

- 4 replace  $\pi^*$  by

$$((\varphi_1?; \alpha_1) \cup \dots \cup (\varphi_n?; \alpha_n))^{\leq n}$$

(uses that  $\text{Prp}_{\alpha_k} = \text{Prp}_{\alpha_l}$  implies  $\alpha_k; \alpha_l = \alpha_l$ )

## DL-PA: complexity

### Theorem

*DL-PA model checking is PSPACE-complete.*

- hardness: encode QBF
- membership: deterministic algorithm working in polynomial space

### Theorem

*DL-PA satisfiability checking is PSPACE-complete.*

- hardness: encode QBF
- membership:
  - 1 satisfiability is in NPSPACE:
    - guess valuation  $V$
    - model check in PSPACE whether  $V \in \|\varphi\|$  (v.s.)
  - 2 NPSPACE = PSPACE [Savitch]

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## Propositional control in one slide

- *Coalition Logic of Propositional Control CL-PC*  
[v.d. Hoek et al. AIJ 2005, JAIR 2010]
  - stem from the language of ATL model checker MOCHA
  - model = valuation + ‘agents control propositional variables’
    - agents can only assign truth values to variables they control
  - language:
    - $\langle J \rangle \varphi$  = “coalition  $J$  can achieve  $\varphi$  (if other agents do nothing)”
  - express capability operator of Coalition Logic CL:
    - $\langle J \rangle [\bar{J}] \varphi$  = “ $J$  can achieve  $\varphi$  (whatever the other agents do)”
  
- in DL-PA:
  - model = valuation (non epistemic)
  - language:
    - $\langle p \leftarrow \top \rangle \varphi$  = “after making  $p$  true,  $\varphi$  will be true”
    - $\langle p \leftarrow \perp \rangle \varphi$  = “after making  $p$  false,  $\varphi$  will be true”
  - ‘get more for the same price’:
    - polynomial translation of CL-PC
    - same complexity as CL-PC
    - extensible: norms, counts-as relation, knowledge, ...

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## Ability to perform an assignment

- finite set of agents  $\mathbb{A} = \{i, j, \dots\}$
- countable set of propositional variables  $\text{Prp}$  is such that

$$\text{Prp} = \text{Prp}^0 \cup \{A_i(p \leftarrow \top), A_i(p \leftarrow \perp) : i \text{ agent}, p \text{ variable}\}$$

- $\text{Prp}^0 =$  *basic* atomic facts
- $A_i(p \leftarrow \top) =$  “*i* is able to make *p* true”
- $A_i(p \leftarrow \perp) =$  “*i* is able to make *p* false”
- basic assignments  $\alpha^0 =$  assignment of variable in  $\text{Prp}^0$
- also possible:
  - higher-order assignments
    - $A_j(p \leftarrow \top) \leftarrow \perp =$  hinder *j* to set *p* to true
    - ...
  - higher-order abilities
    - $A_i(A_j(p \leftarrow \top) \leftarrow \perp) =$  *i* can hinder *j* to set *p* to true
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## Basic capability to achieve a state of affairs

$\diamond_J^{A^0} \varphi$  = “coalition  $J$  can achieve  $\varphi$  by  $J$ 's basic assignments (if other agents do nothing)”

- interpretation of capability operator:

$V \|\diamond_J^{A^0} \|\ V'$  iff there are *basic* assignments  $\alpha_1^0, \dots, \alpha_n^0$  s.th.

(a)  $V \|\alpha_1^0; \dots; \alpha_n^0 \|\ V'$

(b) for every  $\alpha_k^0$  there is  $i \in J$  with  $V \in \|\ A_i(\alpha_k^0) \|\$

(same as Coalition Logic of Propositional Control CL-PC)

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# Basic capability: embedding CL-PC

## Theorem

Formula  $\varphi$  is satisfiable in CL-PC models iff

$$\varphi \wedge \text{Sym}_\varphi \wedge \text{Exh}_\varphi \wedge \text{Excl}_\varphi$$

is DL-PA satisfiable, where:

$$\text{Sym}_\varphi = \bigwedge_{i \in \mathbb{A}_\varphi, p \in \text{Prp}_\varphi} A_i(p \leftarrow \top) \leftrightarrow A_i(p \leftarrow \perp)$$

$$\text{Exh}_\varphi = \begin{cases} \bigwedge_{p \in \text{Prp}_\varphi} \bigvee_{i \in \mathbb{A}} A_i(p \leftarrow \perp) & \text{when } \mathbb{A}_\varphi = \mathbb{A} \\ \bigwedge_{p \in \text{Prp}_\varphi} \bigvee_{i \in \mathbb{A}_\varphi \cup \{j_0\}} A_i(p \leftarrow \perp) & \text{when } \mathbb{A}_\varphi \neq \mathbb{A}, \text{ for some } j_0 \in \mathbb{A} \setminus \mathbb{A}_\varphi \end{cases}$$

$$\text{Excl}_\varphi = \bigwedge_{i, j \in \mathbb{A}_\varphi, i \neq j, p \in \text{Prp}_\varphi} \neg (A_i(p \leftarrow \perp) \wedge A_j(p \leftarrow \perp))$$

$\Rightarrow$  CL-PC can be polynomially embedded into DL-PA plus  $\diamond_J^{A_0}$

# Basic capability: eliminating $\diamond_J^{A^0}$

## Theorem

Let  $\text{Prp}_\varphi = \{p_1, \dots, p_n\}$  the propositional variables occurring in  $\varphi$ .

Then:

$$\diamond_J^{A^0} \varphi \leftrightarrow$$

$$\langle \text{skip} \cup (\bigvee_{i \in J} A_i(p_1 \leftarrow \top)?; p_1 \leftarrow \top) \cup (\bigvee_{i \in J} A_i(p_1 \leftarrow \perp)?; p_1 \leftarrow \perp) \rangle$$

$$\vdots$$

$$\langle \text{skip} \cup (\bigvee_{i \in J} A_i(p_n \leftarrow \top)?; p_n \leftarrow \top) \cup (\bigvee_{i \in J} A_i(p_n \leftarrow \perp)?; p_n \leftarrow \perp) \rangle \varphi$$

$\Rightarrow \diamond_J^{A^0}$  can be polynomially reduced to DL-PA formulas

# Conclusions

- DL-PA = PDL with concrete programs
  - PSPACE complete
- DL-PA, PAL-PA = ‘Swiss knife’ for MAS
  - concrete programs provide for an appropriate modelling in all concrete applications
    - embeds van der Hoek and Wooldridge’s CL-PC
    - distinguish physical and *legal* ability [Herzig et al., CLIMA 2011]
    - Reiter’s solution to the Frame Problem in reasoning about actions [Reiter 1990] can be polynomially encoded in DL-PA [van Ditmarsch et al., JLC 2012]
    - do multi-agent simulation in logic (Schelling’s segregation game) [Gaudou et al., MABS 2011]