Quelques pas autour de la logique spatiale d'arbres

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### Contents

- 1. Motivation
- 2. Information trees

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- 3. The tree logic
- 4. Adjuncts
- 5. Knowledge
- 6. Notes

Semi-structured data

- are unstructured data
- are usually modeled in terms of labeled trees
- are amenable to be accessed through query languages

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Ambient logics

- are modal logics
- are used to describe the properties of mobile computations
- are based on a rich collection of spatio-temporal operators

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The structural part of ambient logics

- is a logic of trees
- is a logic designed to describe properties of labeled trees

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is particularly suitable to describe semi-structured data

Example

- ARTICLES = article[author[Biri] | author[Galmiche] | title[Models] | journal[JLC]] | article[author[Galmiche] | author[LarcheyWendling] | title[Expressivity] | conference[FSTTCS 2006]]
- ▶ from ARTICLES ⊨ ·article[X], X ⊨ ·author[Galmiche] select paper[X]

Reference

 Cardelli, L., Ghelli, G.: A query language based on the ambient logic. ESOP 2001. Springer (2001) 1–22.

Information trees

- are nested multisets
- correspond to unordered trees

Given a set  $\Lambda$  of labels,  $\mathcal{IT}$  is the least collection such that

- $\emptyset$  is in  $\mathcal{IT}$
- if *m* is a label in  $\Lambda$  and *M* is in  $\mathcal{IT}$ , then  $\{\langle m, M \rangle\}$  is in  $\mathcal{IT}$

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• if *M* and *N* are in  $\mathcal{IT}$ , then  $M \biguplus N$  is in  $\mathcal{IT}$ 

Information terms

- are terms borrowed from the ambient calculus
- denote information trees

Given a set  $\Lambda$  of labels, the set of information terms is the least collection such that

- 0 is an information term
- If m is a label in ∧ and F is an information term, then m[F] is an information term
- ► if F and G are information terms, then (F | G) is an information term

Information terms and their information tree meaning

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- $\blacktriangleright \llbracket m[F] \rrbracket = \{ \langle m, \llbracket F \rrbracket \rangle \}$
- $\blacktriangleright \llbracket F \mid G \rrbracket = \llbracket F \rrbracket \biguplus \llbracket G \rrbracket$

Congruence over information terms

$$\blacktriangleright F \equiv F$$

• if 
$$F \equiv G$$
, then  $G \equiv F$ 

• if  $F \equiv G$  and  $G \equiv H$ , then  $F \equiv H$ 

• if 
$$F \equiv G$$
, then  $m[F] \equiv m[G]$ 

- if  $F \equiv G$ , then  $F \mid H \equiv G \mid H$
- if  $F \equiv G$ , then  $H \mid F \equiv H \mid G$
- ► *F* | 0 ≡ *F*
- ▶ 0 | *F* ≡ *F*
- $\blacktriangleright F \mid G \equiv G \mid F$
- $\blacktriangleright (F \mid G) \mid H \equiv F \mid (G \mid H)$

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#### Expressions

 $\blacktriangleright \alpha ::= m \mid x$ 

where m is a label in  $\Lambda$  and x is a label variable

#### Formulas

$$\phi ::= \xi \mid \perp \mid \neg \phi \mid (\phi \lor \psi) \mid \mathbf{0} \mid \alpha[\phi] \mid (\phi \mid \psi) \mid \mathcal{X} \mid \exists x \cdot \phi \mid \exists \mathcal{X} \cdot \phi \mid \alpha \sim \beta \mid \mu \xi \cdot \phi$$

where  $\xi$  is a recursion variable and  $\mathcal{X}$  is a tree variable

#### Reference

 Cardelli, L., Gordon, A.: Anytime, anywhere: modal logics for mobile ambients. POPL 2000. ACM (2000) 365–377.

Semantic map

- interpretation  $\rho : x \mapsto \rho(x) \in \Lambda$  of label variables
- interpretation  $\sigma : \mathcal{X} \mapsto \sigma(\mathcal{X}) \in \mathcal{IT}$  of tree variables
- interpretation  $\tau: \xi \mapsto \tau(\xi) \in 2^{\mathcal{IT}}$  of recursion variables

Interpretation of formulas

$$\blacktriangleright \llbracket \cdot \rrbracket_{\rho,\sigma,\tau} : \phi \mapsto \llbracket \phi \rrbracket_{\rho,\sigma,\tau} \in \mathbf{2}^{\mathcal{IT}}$$

Satisfaction

► *F* satisfies  $\phi$  under  $\rho$ ,  $\sigma$  and  $\tau$ , denoted *F*  $\models_{\rho,\sigma,\tau} \phi$ , iff  $\llbracket F \rrbracket \in \llbracket \phi \rrbracket_{\rho,\sigma,\tau}$ 

Formulas as sets of information trees

• 
$$\llbracket \xi \rrbracket_{\rho,\sigma,\tau} = \tau(\xi)$$
  
•  $\llbracket \bot \rrbracket_{\rho,\sigma,\tau} = \emptyset$   
•  $\llbracket \neg \phi \rrbracket_{\rho,\sigma,\tau} = \mathcal{IT} \setminus \llbracket \phi \rrbracket_{\rho,\sigma,\tau}$   
•  $\llbracket \phi \lor \psi \rrbracket_{\rho,\sigma,\tau} = \llbracket \phi \rrbracket_{\rho,\sigma,\tau} \cup \llbracket \psi \rrbracket_{\rho,\sigma,\tau}$   
•  $\llbracket 0 \rrbracket_{\rho,\sigma,\tau} = \{ \emptyset \}$   
•  $\llbracket \alpha[\phi] \rrbracket_{\rho,\sigma,\tau} = \{ \langle \rho(\alpha), M \rangle : M \text{ is in } \llbracket \phi \rrbracket_{\rho,\sigma,\tau} \}$   
•  $\llbracket \alpha[\phi] \rrbracket_{\rho,\sigma,\tau} = \{ \langle \rho(\alpha), M \rangle : M \text{ is in } \llbracket \phi \rrbracket_{\rho,\sigma,\tau} \}$   
•  $\llbracket \alpha[\phi] \rrbracket_{\rho,\sigma,\tau} = \{ \langle \rho(\alpha), M \rangle : M \text{ is in } \llbracket \phi \rrbracket_{\rho,\sigma,\tau} \}$   
•  $\llbracket X \rrbracket_{\rho,\sigma,\tau} = \{ \langle \mu \Downarrow M \lor N : M \text{ is in } \llbracket \phi \rrbracket_{\rho,\sigma,\tau} \text{ and } N \text{ is in } \llbracket \psi \rrbracket_{\rho,\sigma,\tau} \}$   
•  $\llbracket X \rrbracket_{\rho,\sigma,\tau} = \{ \sigma(\mathcal{X}) \}$   
•  $\llbracket \exists X \cdot \phi \rrbracket_{\rho,\sigma,\tau} = \bigcup \{ \llbracket \phi \rrbracket_{\rho,[X:=M],\tau} : M \text{ is in } \mathcal{IT} \}$   
•  $\llbracket \alpha \sim \beta \rrbracket_{\rho,\sigma,\tau} = \inf \rho(\alpha) = \rho(\beta) \text{ then } \mathcal{IT} \text{ else } \emptyset$   
•  $\llbracket \mu \xi \cdot \phi \rrbracket_{\rho,\sigma,\tau} = \bigcap \{ S : S \text{ contains } \llbracket \phi \rrbracket_{\rho,\sigma,\tau} [\xi:=S] \}$ 

Some properties of satisfaction

•  $F \models_{\rho,\sigma,\tau} \xi$  iff **[[***F*]] is in  $\tau(\xi)$ 

$$\blacktriangleright \mathsf{F} \not\models_{\rho,\sigma,\tau} \bot$$

$$\blacktriangleright F \models_{\rho,\sigma,\tau} \neg \phi \text{ iff } F \not\models_{\rho,\sigma,\tau} \phi$$

$$\blacktriangleright F \models_{\rho,\sigma,\tau} \phi \lor \psi \text{ iff } F \models_{\rho,\sigma,\tau} \phi \text{ or } F \models_{\rho,\sigma,\tau} \psi$$

• 
$$F \models_{\rho,\sigma,\tau} 0$$
 iff  $F \equiv 0$ 

- $F \models_{\rho,\sigma,\tau} \alpha[\phi]$  iff for some  $G, F \equiv \rho(\alpha)[G]$  and  $G \models_{\rho,\sigma,\tau} \phi$
- ►  $F \models_{\rho,\sigma,\tau} \phi \mid \psi$  iff for some  $G, H, F \equiv G \mid H, G \models_{\rho,\sigma,\tau} \phi$  and  $H \models_{\rho,\sigma,\tau} \psi$
- $F \models_{\rho,\sigma,\tau} \mathcal{X}$  iff **[[F]]** equals  $\sigma(\mathcal{X})$
- ►  $F \models_{\rho,\sigma,\tau} \exists x \cdot \phi$  iff for some label *m* in  $\Lambda$ ,  $F \models_{\rho[x:=m],\sigma,\tau} \phi$

- $\blacktriangleright F \models_{\rho,\sigma,\tau} \exists \mathcal{X} \cdot \phi \text{ iff for some } M \text{ in } \mathcal{IT}, F \models_{\rho,\sigma[\mathcal{X}:=M],\tau} \phi$
- $\blacktriangleright F \models_{\rho,\sigma,\tau} \alpha \sim \beta \text{ iff } \rho(\alpha) \text{ equals } \rho(\beta)$
- $\blacktriangleright F \models_{\rho,\sigma,\tau} \mu \xi \cdot \phi \text{ iff } F \models_{\rho,\sigma,\tau} \phi[\xi/\mu \xi \cdot \phi]$

### Derived formulas

- ▶  $\alpha[\Rightarrow \phi]$  is  $\neg \alpha[\neg \phi]$
- $(\phi \parallel \psi)$  is  $\neg (\neg \phi \mid \neg \psi)$
- $\blacktriangleright \forall x \cdot \phi \text{ is } \neg \exists x \cdot \neg \phi$
- $\blacktriangleright \forall \mathcal{X} \cdot \phi \text{ is } \neg \exists \mathcal{X} \cdot \neg \phi$
- $\nu \xi \cdot \phi$  is  $\neg \mu \xi \cdot \neg \phi[\xi/\neg \xi]$

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•  $\phi^*$  is  $\mu \xi \cdot \mathbf{0} \lor (\phi \mid \xi)$ 

#### Some valid equivalences

- $\blacktriangleright \ \alpha[\phi] \leftrightarrow \alpha[\top] \land \alpha[\Rightarrow \phi]$
- $\blacktriangleright \ \alpha[\Rightarrow \phi] \leftrightarrow (\alpha[\top] \to \alpha[\phi])$
- $\alpha[\bot] \leftrightarrow \bot$
- $\blacktriangleright \alpha [ \Rightarrow \top ] \leftrightarrow \top$
- $\blacktriangleright \ \alpha[\phi \lor \psi] \leftrightarrow \alpha[\phi] \lor \alpha[\psi]$
- $\blacktriangleright \ \alpha [\Rightarrow \phi \lor \psi] \leftrightarrow \alpha [\Rightarrow \phi] \lor \alpha [\Rightarrow \psi]$
- $\blacktriangleright \ \alpha[\phi \land \psi] \leftrightarrow \alpha[\phi] \land \alpha[\psi]$
- $\blacktriangleright \ \alpha[\Rightarrow \phi \land \psi] \leftrightarrow \alpha[\Rightarrow \phi] \land \alpha[\Rightarrow \psi]$
- $\alpha[Qx \cdot \phi] \leftrightarrow Qx \cdot \alpha[\phi]$  if  $\alpha \neq x$
- $\alpha[\Rightarrow Qx \cdot \phi] \leftrightarrow Qx \cdot \alpha[\Rightarrow \phi] \text{ if } \alpha \neq x$

Some valid equivalences

- $\begin{array}{l} \bullet \phi \mid \bot \leftrightarrow \bot \\ \bullet \phi \mid \top \leftrightarrow \top \\ \bullet \phi \mid (\psi \lor \chi) \leftrightarrow \phi \mid \psi \lor \phi \mid \chi \\ \bullet \phi \mid (\psi \land \chi) \leftrightarrow \phi \mid \psi \land \phi \mid \chi \\ \bullet \phi \mid \psi \leftrightarrow \psi \mid \phi \\ \bullet \phi \mid \psi \leftrightarrow \psi \mid \phi \end{array}$
- $\blacktriangleright (\phi \mid \psi) \mid \chi \leftrightarrow \phi \mid (\psi \mid \chi)$
- $\blacktriangleright (\phi \parallel \psi) \parallel \chi \leftrightarrow \phi \parallel (\psi \parallel \chi)$
- $\blacktriangleright \phi \mid Qx \cdot \psi \leftrightarrow Qx \cdot \phi \mid \psi \text{ if } x \notin FV(\phi)$
- $\blacktriangleright \phi \parallel Qx \cdot \psi \leftrightarrow Qx \cdot \phi \parallel \psi \text{ if } x \notin FV(\phi)$

Questions

- axiomatization/completess ?
- decidability/complexity ?
- variants

$$\bullet \phi ::= \xi \mid \perp \mid \neg \phi \mid (\phi \lor \psi) \mid \mathbf{0} \mid \alpha[\phi] \mid (\phi \mid \psi) \mid \mu \xi \cdot \phi$$

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 $\bullet \phi ::= \bot \mid \neg \phi \mid (\phi \lor \psi) \mid \mathbf{0} \mid \alpha[\phi] \mid (\phi \mid \psi) \mid \phi^{\star}$ 

#### Formulas

 $\blacktriangleright \phi ::= \bot \mid \neg \phi \mid (\phi \lor \psi) \mid \mathbf{0} \mid m[\phi] \mid (\phi \mid \psi) \mid \phi @m \mid (\phi \triangleright \psi)$ 

#### Reference

- Calcagno, C., Cardelli, L., Gordon, A.: Deciding validity in a spatial logic for trees. Journal of Functional Programming 15 (2005) 543–572.
- Lozes, E.: Elimination of spatial connectives in static spatial logics. Theoretical Computer Science 330 (2005) 475–499.

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Interpretation of formulas

 $\blacktriangleright \ \llbracket \cdot \ \rrbracket : \phi \mapsto \llbracket \phi \rrbracket \in \mathbf{2}^{\mathcal{IT}}$ 

Satisfaction

▶ *F* satisfies  $\phi$ , denoted *F*  $\models \phi$ , iff **[***F***]**  $\in$  **[** $\phi$ **]** 

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Formulas as sets of information trees

- ▶ [[⊥]] = ∅
- $\blacktriangleright \llbracket \neg \phi \rrbracket = \mathcal{IT} \setminus \llbracket \phi \rrbracket$
- $\blacktriangleright \llbracket \phi \lor \psi \rrbracket = \llbracket \phi \rrbracket \cup \llbracket \psi \rrbracket$
- ▶ [[0]] = {∅}
- $\llbracket m[\phi] \rrbracket = \{ \langle m, M \rangle : M \text{ is in } \llbracket \phi \rrbracket \}$
- $\llbracket \phi \mid \psi \rrbracket = \{ M \biguplus N : M \text{ is in } \llbracket \phi \rrbracket \text{ and } N \text{ is in } \llbracket \psi \rrbracket \}$
- $\llbracket \phi @m \rrbracket = \{ M: \langle m, M \rangle \text{ is in } \llbracket \phi \rrbracket \}$
- $\llbracket \phi \triangleright \psi \rrbracket = \{ M: \text{ for every } N \text{ in } \llbracket \phi \rrbracket, M \biguplus N \text{ is in } \llbracket \psi \rrbracket \}$

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Information trees as formulas

- ▶ φ(0) = 0
- $\blacktriangleright \varphi(m[F]) = m[\varphi(F)]$
- $\blacktriangleright \varphi(F \mid G) = \varphi(F) \mid \varphi(G)$

Validity vs model checking

- $\phi$  is valid iff  $\mathbf{0} \models \top \triangleright \phi$
- $F \models \phi$  iff  $\varphi(F) \rightarrow \phi$  is valid

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Bisimilarity between information terms

• if  $F \simeq_i G$  then either i = 0, or

- $F \equiv 0$  iff  $G \equiv 0$
- for every label *m* in ∧ and for every information term *F'*, if *F* ≡ *m*[*F'*] then for some information term *G'*, *G* ≡ *m*[*G'*] and *F'* ≃<sub>*i*-1</sub> *G'*
- for every label *m* in ∧ and for every information term *G'*, if *G* ≡ *m*[*G'*] then for some information term *F'*, *F* ≡ *m*[*F'*] and *F'* ≃<sub>*i*-1</sub> *G'*
- for every information term F', F", if F ≡ F' | F" then for some information term G', G", G ≡ G' | G", F' ≃<sub>i-1</sub> G' and F" ≃<sub>i-1</sub> G"
- For every information term G', G", if G ≡ G' | G" then for some information term F', F", F ≡ F' | F", F' ≃<sub>i-1</sub> G' and F" ≃<sub>i-1</sub> G"

Ultrametric distance between information terms •  $d(F, G) = \sup\{2^{-i}: i \in \mathbb{N}\}$  is such that  $F \not\simeq_i G\}$ 

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Remark

• 
$$d(F, G) < 2^{-i}$$
 iff  $F \simeq_i G$ 

Properties of the ultrametric distance

- complete
- totally bounded
- compact
- separable

Theorem (Calcagno et al., 2005; Lozes, 2005)

every formula is equivalent to some adjunct-free formula

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validity and model checking are decidable

Questions

- axiomatization/completess ?
- decidability/complexity ?
- variants
  - $\bullet \phi ::= \xi \mid \perp \mid \neg \phi \mid (\phi \lor \psi) \mid \mathbf{0} \mid \alpha[\phi] \mid (\phi \mid \psi) \mid \phi @m \mid (\phi \triangleright \psi) \mid \\ \mu \xi \cdot \phi$
  - $\blacktriangleright \phi ::= \bot \mid \neg \phi \mid (\phi \lor \psi) \mid \mathbf{0} \mid \alpha[\phi] \mid (\phi \mid \psi) \mid \phi @m \mid (\phi \triangleright \psi) \mid \phi^{\star}$

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# Knowledge

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### Notes

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